

G_2 -manifolds

The octonions \mathbb{O} is the set of pairs of quaternions $(a, b) \in \mathbb{H} \times \mathbb{H}$ with product:

$$(a, b) \cdot (c, d) := (ac - \bar{d}b, da + b\bar{c}).$$

The product is neither commutative nor associative. Defining $\bar{x} := (\bar{a}, -b)$ for $x = (a, b) \in \mathbb{O}$, we define

$$\text{Im}(x) = \frac{1}{2}(x - \bar{x}), \quad \text{Re}(x) = \frac{1}{2}(x + \bar{x}).$$

There is an inner product on \mathbb{O} defined by $\langle x, y \rangle = \text{Re}(x \bar{y})$ corresponding to the standard inner product under the identification $\mathbb{O} = \mathbb{H} \oplus \mathbb{H} = \mathbb{R}^4 \oplus \mathbb{R}^4 = \mathbb{R}^8$.

On $\mathbb{R}^7 = \text{Im}(\mathbb{O})$, we can also consider the 3-form

$$\varphi_0(x, y, z) = \langle x \cdot y, z \rangle.$$

Definition: The group G_2 is the stabilizer of φ_0 with respect to the natural action of $GL(7, \mathbb{R})$ on $\Lambda^3((\mathbb{R}^7)^*)$. It can also be seen as the group of automorphisms of (\mathbb{O}, \cdot) . In particular,

- Facts: 1) G_2 is ^{compact} simply connected of dimension 14. $G_2 \subset SO(7)$.
 2) The $GL(7, \mathbb{R})$ orbit of φ_0 is open.

Definition: A G_2 -structure on an oriented 7-manifold M is a reduction of the structure group of its frame bundle to G_2 . This corresponds to finding a 3-form $\varphi \in \Omega^3(M)$ such that for each $m \in M$, there is a linear oriented map $\nu_m: \mathbb{R}^7 \rightarrow T_m M$ such that $\varphi_m = \nu_m^*(\varphi|_{\Lambda^3(T_m M)})$. Since $G_2 \subset SO(7)$, it also induces a Riemannian metric g_φ and a 4-form $\ast\varphi$, where \ast is the Hodge \ast of g_φ .

The torsion of a G_2 -structure is $\nabla\varphi$, where ∇ is the Levi-Civita connection of g_φ .

Definition: A G_2 -manifold is a Riemannian manifold of dimension 7 (M, g) with holonomy contained in G_2 . In particular, there is an induced G_2 -structure and the 3-form φ can be chosen so that $g = g_\varphi$ and $\nabla\varphi = 0$.

A G_2 -manifold is irreducible if its holonomy is precisely G_2 .

Fact: G_2 -manifolds are automatically Ricci-flat.

Proposition: The following are equivalent on an oriented 7-manifold equipped with G_2 -structure (φ, g_φ) :

- 1) (φ, g_φ) is torsion-free;
- 2) (M, g_φ) is a b_2 -manifold;
- 3) $\nabla\varphi = 0$ on M ;
- 4) $d\varphi = d^*\varphi = 0$
- 5) $d\varphi = d \times \varphi = 0$.

Examples: Bryant-Salamon 1989: First complete examples (asymptotically conical asymptoticity are examples)
Joyce 1996: First compact examples; Kummer type construction.

$SU(3)$ -structure and Calabi-Yau 3-folds

Definition: An $SU(3)$ -structure on a 6-dimensional manifold B is a reduction of the structure group of its frame bundle to $SU(3)$.

Notice $SU(3)$ can be seen as the subgroup of $GL(3, \mathbb{C})$ preserving the canonical symplectic form and holomorphic form on \mathbb{C}^3 :

$$\omega_0 = \frac{i}{2} \sum_{k=1}^3 dz_k \wedge d\bar{z}_k, \quad \Omega_0 = dz_1 \wedge dz_2 \wedge dz_3$$

It preserves also the complex structure of \mathbb{C}^3 and its canonical metric. As such, a $SU(3)$ structure induce a Riemannian metric g_B on B , an almost complex structure J , a 2-form ω and a complex 3-form Ω . Since

$$\omega_0 \wedge \text{Re} \Omega_0 = 0 \text{ and } \frac{1}{6} \omega_0^3 = \frac{1}{4} \text{Re} \Omega_0 \wedge \text{Im} \Omega_0,$$

notice that the same relations holds for ω and Ω on B :

$$\omega \wedge \text{Re} \Omega = 0, \quad \frac{1}{6} \omega^3 = \frac{1}{4} \text{Re} \Omega \wedge \text{Im} \Omega$$

Definition: A Calabi-Yau 3-fold is a 6-dimensional manifold B endowed with $SU(3)$ -structure (ω, Ω) such that $d\omega = d\Omega = 0$. We may equivalently that (ω, Ω) is a torsion-free $SU(3)$ -structure. In this case, ω and Ω are parallel with respect to the

Levi-Civita connection of the induced Riemannian metric. In particular, the complex structure is also parallel with respect to the Levi-Civita connection, so that the holonomy of the induced metric is contained in $SU(3)$.

Asymptotically locally conical (ALC) G_2 -manifolds

A Riemannian metric g on M is ALC if outside a compact set it is asymptotic to a S^1 -invariant metric:

$$g_{ALC} = \pi^* g_C + \theta^2$$

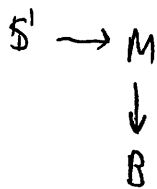
with (C, g_C) a cone, $\pi: L \rightarrow C$ a circle bundle and θ connection 1-form for L corresponding to the pull-back of a connection 1-form on $L|_{[1, \infty) \times S}$ where $C = [0, \infty) \times S$ and S is the link of the cone: $L = pr_2^*(L|_{[1, \infty) \times S})$, $\theta = pr_2^*(\theta_1)$, $pr_2: [0, \infty) \times S \rightarrow S$ the projection on the second factor.

In particular, the volume growth of a ball of radius r in (M, g) is $O(r^{\dim M - 1})$.

Example: An ALF metric is ALC with $C = \mathbb{R}^3/\Gamma$ for a finite group $\Gamma \subset O(3)$.

The strategy of F-H-N to construct complete G_2 -manifolds is to start with an

Asymptotically conical (AC) Calabi-Yau 3-fold $(B, g_B, \omega_B, \Omega_B)$ and consider an S^1 -invariant G_2 -structure on a circle bundle



we can consider an

On M , S^1 -invariant G_2 -structure of the form

$$\varphi = \theta \wedge \omega + h^{3/4} \operatorname{Re} \Omega, \text{ where } (\omega, \Omega) \text{ is a } SU(3) \text{ structure on } B, h \text{ is a positive function on } B \text{ and } \theta \text{ is a connection 1-form for } M \rightarrow B.$$

To be torsion-free, $(\omega, \Omega, \theta, h)$ must satisfy a coupled system of nonlinear PDE (Appertoux-Salamon).
This is hard to solve in general.

Idea: take the adiabatic limits where the length ε of the circle tends to zero and the metric Gromov-Hausdorff converges to a Calabi-Yau metric on B . Linearizing the rescaled Appertoux-Salamon equations at $\varepsilon=0$ gives a coupled linear PDE for an infinitesimal deformation $(\sigma, \rho+i\hat{\rho})$ of the $SU(3)$ structure (ω_0, Ω_0) , a function h and a connection 1-form θ

Ansatz: 1) (B, ω_ε) is a fixed symplectic manifold $\Rightarrow \sigma=0$
2) h is constant, say $h=1$.

In this case, two of the linearized equations are

$$d\theta \wedge \omega_0^2 = 0, \quad d\theta \wedge \operatorname{Re} \Omega_0 = 0 \quad (\text{HYM}) \quad (d\theta \text{ is a primitive } (1,1)\text{-form})$$

Step 1: Find a solution θ of HYM \rightsquigarrow consider $\varphi_\varepsilon = \varepsilon \theta \wedge \omega_0 + \operatorname{Re} \Omega_0$ an S^1 -invariant G_2 -structure

Problem: $d\varphi_\varepsilon = \varepsilon d\theta \wedge \omega_0$ is not closed in general.

Solution: Find $\rho+i\hat{\rho}$ such that $d\rho = -d\theta \wedge \omega_0, d\hat{\rho} = 0$. (LAS).

$$\Rightarrow \varphi_\varepsilon^{(1)} = \varepsilon \theta \wedge \omega_0 + \operatorname{Re} \Omega_0 + \varepsilon \rho \text{ are closed.}$$

This imposes the constraint $c_1(M) \cup [\omega_0] = 0 \in H^4(B)$.

Assuming this, (LAS) can be solved formulating it as an elliptic PDE:

$$(d+d^*)\rho = *d\theta \quad \text{with } \hat{\rho} := -*\rho \text{ for } \rho \text{ a solution.}$$

This yields an approximate 1-parameter family of G_2 -structures

$$\varphi_\varepsilon^{(1)} = \varepsilon \theta \wedge \omega_0 + \operatorname{Re} \Omega_0 + \varepsilon \rho \quad \text{with torsion of order } O(\varepsilon^2).$$

To construct an exact solution, the idea is then to iterate this construction to obtain a formal solution as a power series in ε and check the power series actually converges.